## Motor Calculations

Motor selected for driving the wheels (total number 2, one for each wheel):
\#164786, MOTOR, GEAR, 300RPM, 12VDC @ 25MA

Preliminary test:
No load speed at 6 V: 142.1 rpm;
at 9 V : 218.0 rpm .

Assume that when driving the wheel, the motor would spin at $60-70 \%$ of the maximum efficiency speed, and that we would use a pair of wheels with the diameter $=3.75 \mathrm{in}$. Then the estimated full speed of our robot is approx. equal to:
$142.1 \mathrm{rpm} / 6 \mathrm{~V}$ * 12 V * $60 \%$ * ( $\pi$ * 3.75 in * $25.4 / 1000 \mathrm{~m} / \mathrm{in}) /(60 \mathrm{~s} / \mathrm{min})=0.85 \mathrm{~m} / \mathrm{s}$

