Motor Calculations

Motor selected for driving the wheels (total number 2, one for each wheel): #164786, MOTOR, GEAR, 300RPM, 12VDC @ 25MA

Preliminary test:

No load speed at 6 V: 142.1 rpm; at 9 V: 218.0 rpm.

Assume that when driving the wheel, the motor would spin at 60-70% of the maximum efficiency speed, and that we would use a pair of wheels with the diameter = 3.75 in. Then the estimated full speed of our robot is approx. equal to:

142.1 rpm /6V * 12V * 60% * (π * 3.75 in * 25.4/1000 m/in) / (60 s/min) = 0.85 m/s